

Energy Problems – Set 1

For each vector pair below, sketch the pair and calculate $\vec{A} \cdot \vec{B}$.

a. $\vec{A} = 3\hat{i} + 6\hat{j}$

$\vec{B} = -4\hat{i} + 2\hat{j}$

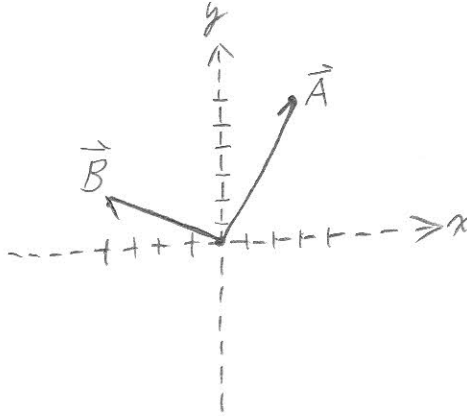
b. $|\vec{A}| = 2\sqrt{10}, \theta = -71.6^\circ$

$\vec{B} = -3\hat{i} + 1\hat{j}$

c. $\vec{A} = -5\hat{i} + 2\hat{j}$

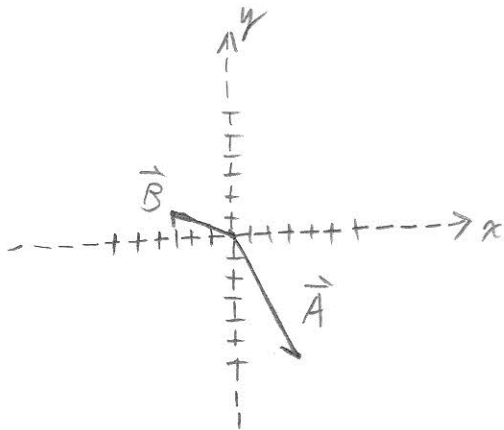
$\vec{B} = -3\hat{i} + 1\hat{j}$

d)



$$\vec{A} \cdot \vec{B} = (-3 \cdot 4 + 6 \cdot 2) = \underline{0}$$

b)

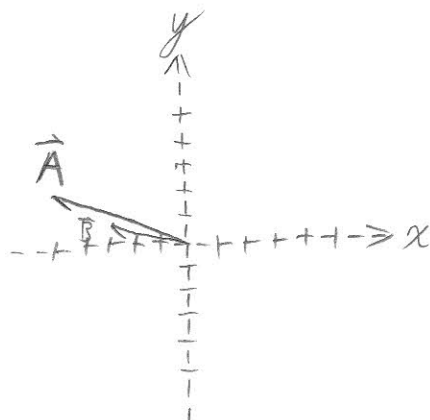


$$A_x = 2\sqrt{10} \cos(-71.6) = 2.0$$

$$A_y = 2\sqrt{10} \sin(-71.6) = -6.0$$

$$\vec{A} \cdot \vec{B} = (2 \cdot 3 - 6 \cdot 1) = \underline{-12}$$

c)



$$\vec{A} \cdot \vec{B} = (+15 + 2) = \underline{17}$$

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For each vector pair in the previous question, use your calculated dot product to find the angle θ between \vec{A} and \vec{B} .

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta \Rightarrow \theta = \cos^{-1} \left(\frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} \right)$$

$$a) |\vec{A}| = (3^2 + 6^2)^{1/2} = 6.7, \quad |\vec{B}| = (4^2 + 2^2)^{1/2} = 4.5$$

$$\theta = \cos^{-1} \left(\frac{0}{(6.7)(4.5)} \right) = \boxed{90}$$

$$b) |\vec{A}| = 2\sqrt{10}, \quad |\vec{B}| = (3^2 + 1^2)^{1/2} = \sqrt{10}, \quad \theta = \cos^{-1} \left(\frac{-12}{2\sqrt{10}\sqrt{10}} \right) = 127^\circ$$

$$c) |\vec{A}| = (5^2 + 2^2)^{1/2} = 5.4, \quad |\vec{B}| = (3^2 + 1^2)^{1/2} = 3.2$$

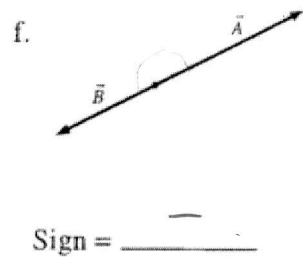
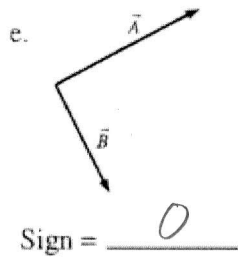
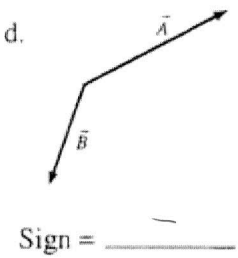
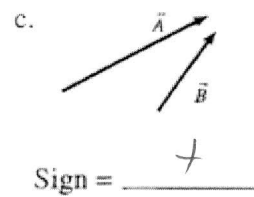
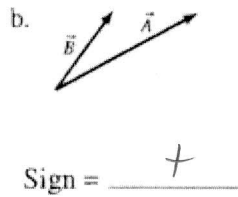
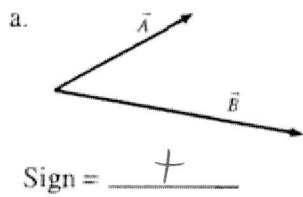
$$\theta = \cos^{-1} \left(\frac{17}{(5.4)(3.2)} \right) = 10.3^\circ$$

3. Which pairs of vectors are orthogonal? What is the dot product of the orthogonal pairs?

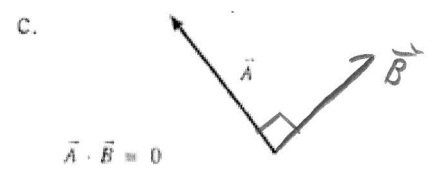
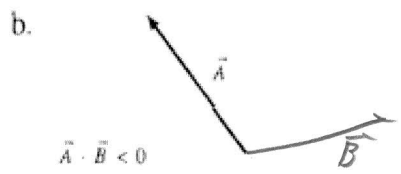
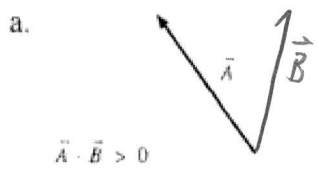
Pair a is orthogonal. When $\vec{A} \perp \vec{B}$, $\vec{A} \cdot \vec{B} = 0$

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For each pair of vectors below, is the sign of $\vec{A} \cdot \vec{B}$ positive, negative or zero?

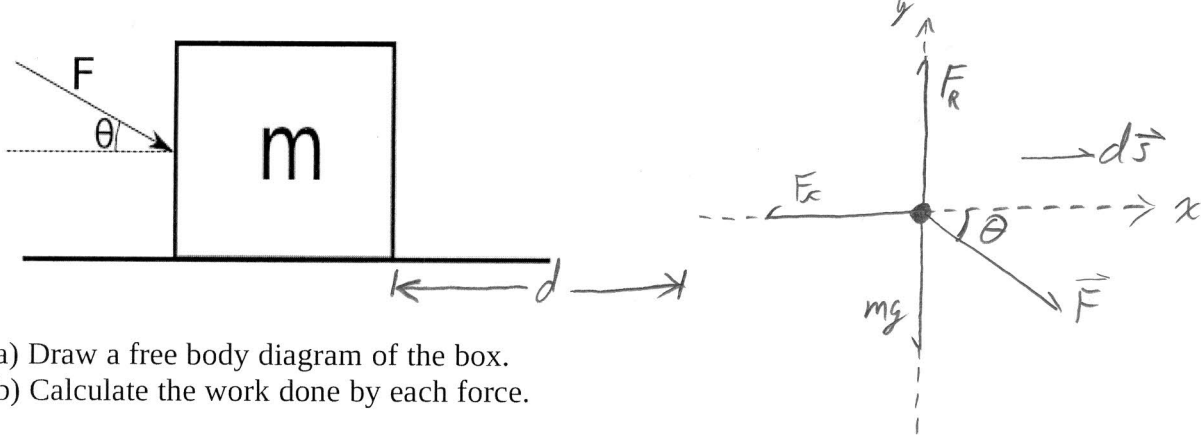


Each of the diagrams below shows a vector \vec{A} . Draw and label a vector \vec{B} that will cause $\vec{A} \cdot \vec{B}$ to have the indicated sign.



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A box with mass m , initially at rest, is pushed a distance d along a surface with a force F making an angle θ with the horizontal. The coefficient of friction between the box and the surface is μ_k .



- Draw a free body diagram of the box.
- Calculate the work done by each force.

$$W = \int \vec{F} \cdot d\vec{s}, \quad d\vec{s} = dx \hat{x}$$

$$F_R: W = \int_0^d (F_R \hat{j}) \cdot (dx \hat{x}) \Rightarrow W = F_R (\hat{x} \cdot \hat{j}) \int_0^d dx \Rightarrow \boxed{W=0}$$

$$mg: W = \int_0^d (-mg \hat{j}) \cdot (dx \hat{x}) \Rightarrow W = -mg (\hat{x} \cdot \hat{j}) \int_0^d dx \Rightarrow \boxed{W=0}$$

$$F: W = \int_0^d (\vec{F}) \cdot (dx \hat{x}) \Rightarrow W = \vec{F} \cdot \hat{x} \int_0^d dx \Rightarrow W = |\vec{F}| |\hat{x}| \cos \theta \int_0^d dx$$

$$\boxed{W = Fd \cos \theta}$$

- or -

$$W = \int_0^d (F \cos \theta \hat{x} + F \sin \theta \hat{j}) \cdot (dx \hat{x})$$

$$= \int_0^d F \cos \theta \hat{x} \cdot \hat{x} dx + \int_0^d F \sin \theta \hat{j} \cdot \hat{x} dx = Fd \cos \theta$$

(2)

$$F_x: W = \int (-F_x \hat{x}) \cdot (dx \hat{x}) = -F_x \hat{x} \cdot \hat{x} \int_0^d dx \Rightarrow \boxed{W = -F_x d}$$

From NSL, we find the frictional force

NSL

$$y: F_R - mg - F \sin \theta = 0$$

$$\Rightarrow F_R = mg + F \sin \theta \Rightarrow \boxed{F_f = \mu_k (mg + F \sin \theta)}$$

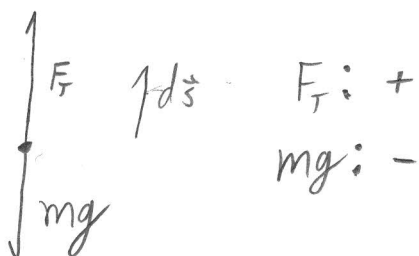
and $\boxed{W_{F_f} = -\mu_k (mg + F \sin \theta) d}$

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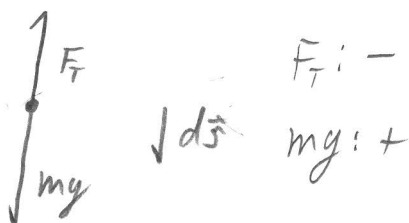
For each situation described below:

- Draw a free body diagram.
- Make a table next to each free body diagram showing each force and whether the work is positive, negative, or zero

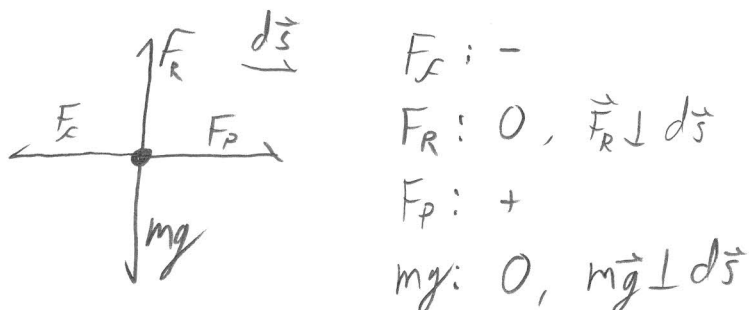
1. An elevator being pulled upward by a cable.



2. The same elevator on the trip down.



3. A mover pushing a box across a rough floor.



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4. A ball thrown straight up. Consider the ball from the point just after it leaves your hand until the highest point in its trajectory.



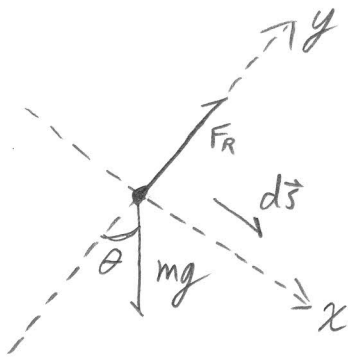
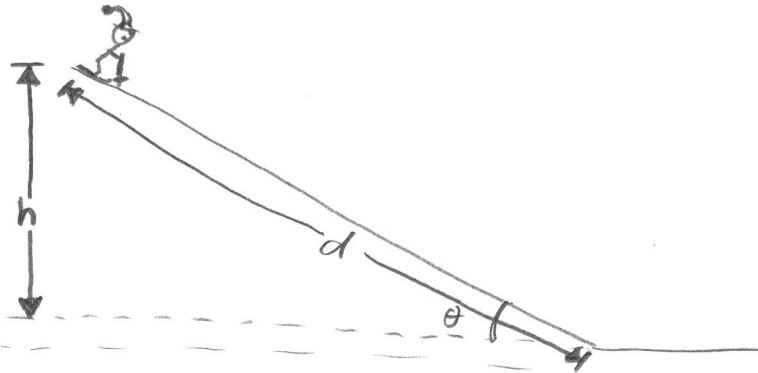
5. A mass on a string swings one revolution in a circle on a horizontal, frictionless table at a constant speed.



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A skier of mass m skis a distance L down a frictionless hill that has a constant angle of inclination θ . The top of the hill is a vertical distance h above the bottom of the hill.

- Use the integral form of the definition of work to find an expression for the work done on the skier by each of the forces involved.
- Find an expression for the **total** work, W_{net} , done on the skier. Your expression should be in terms of m , g , and h only.



$$d\vec{s} = dx\hat{x}$$

$$F_R: W_{F_R} = \int_0^d \vec{F}_R \cdot d\vec{s} = \int_0^d (F_R \hat{y}) \cdot (dx \hat{x})$$

$$= F_R (\hat{y} \cdot \hat{x}) \int_0^d dx = \underline{0}$$

$$W_{NET} = W_{F_R} + W_g$$

$$= 0 + mgd \sin\theta$$

$$W_{NET} = mgh$$

$$mg: W_g = \int_0^d m\vec{g} \cdot d\vec{s}$$

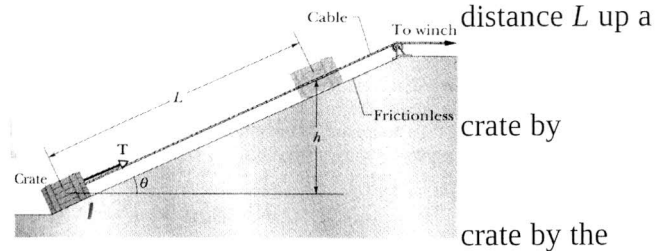
$$= \int_0^d (mg \sin\theta \hat{x} + mg \cos\theta \hat{y}) \cdot (dx \hat{x})$$

$$= mg \sin\theta (\hat{x} \cdot \hat{x}) \int_0^d dx$$

$$W = mgd \sin\theta$$

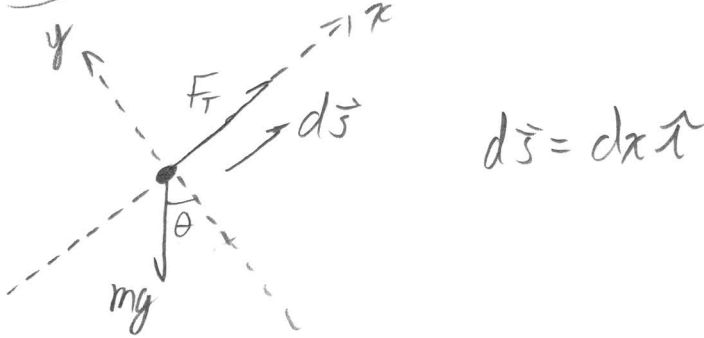
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An initially stationary crate of mass m is pulled a frictionless ramp to a height h where it stops.



a) Find an expression for the work W_g done on the gravity during the lift in terms of m , h , and g .

b) Find an expression for the work W_T done on the tension T in the cable during the lift in terms of m , h and g .

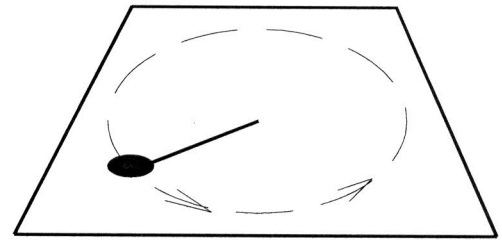


$$\begin{aligned}
 \text{a) } W_g &= \int m\vec{g} \cdot d\vec{s} = \int_0^L (-mg \sin\theta \hat{x} - mg \cos\theta \hat{y}) (dx \hat{x}) \\
 &= -mg \sin\theta (\hat{x} \cdot \hat{x}) \int_0^L dx = -mgL \sin\theta
 \end{aligned}$$

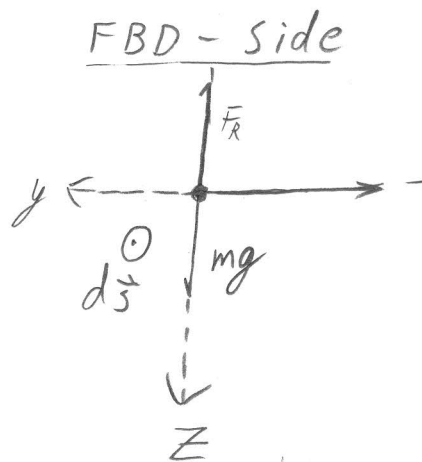
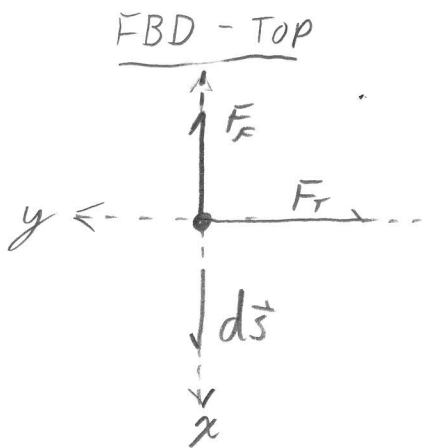
$$\boxed{W_g = -mgh}$$

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A particle of mass m moves in a horizontal circle of radius R on a rough table. It is attached to a string fixed at the center of the circle. The coefficient of friction between the mass and the table is μ_k .



- Draw a free body diagram of the puck.
- Calculate the work done by each force.
- Calculate the net work.



$$d\vec{s} = dx\hat{x}$$

NSL

$$F_R - mg = 0$$

$$\Rightarrow \underline{F_R = mg}$$

$$F_R: W_{F_R} = \int_0^{2\pi R} (\vec{F}_R \hat{k}) \cdot (dx\hat{x}) = -F_R (\hat{k} \cdot \hat{x}) \int_0^{2\pi R} dx = \underline{0} \quad \hat{k} \cdot \hat{x} = 0$$

$$mg: W_g = \int_0^{2\pi R} (mg\hat{k}) \cdot (dx\hat{x}) = mg (\hat{k} \cdot \hat{x}) \int_0^{2\pi R} dx = \underline{0} \quad \hat{k} \cdot \hat{x} = 0$$

$$F_T: W_{F_T} = \int_0^{2\pi R} (-F_T \hat{y}) \cdot (dx\hat{x}) = -F_T (\hat{y} \cdot \hat{x}) \int_0^{2\pi R} dx = \underline{0} \quad \hat{y} \cdot \hat{x} = 0$$

$$F_f: W_{F_f} = \int_0^{2\pi R} (-\mu_k F_R \hat{x}) \cdot (dx\hat{x}) = -\mu_k mg (\hat{x} \cdot \hat{x}) \int_0^{2\pi R} dx = \boxed{-\mu_k mg 2\pi R}$$

$$W_{net} = -\mu_k mg 2\pi R$$